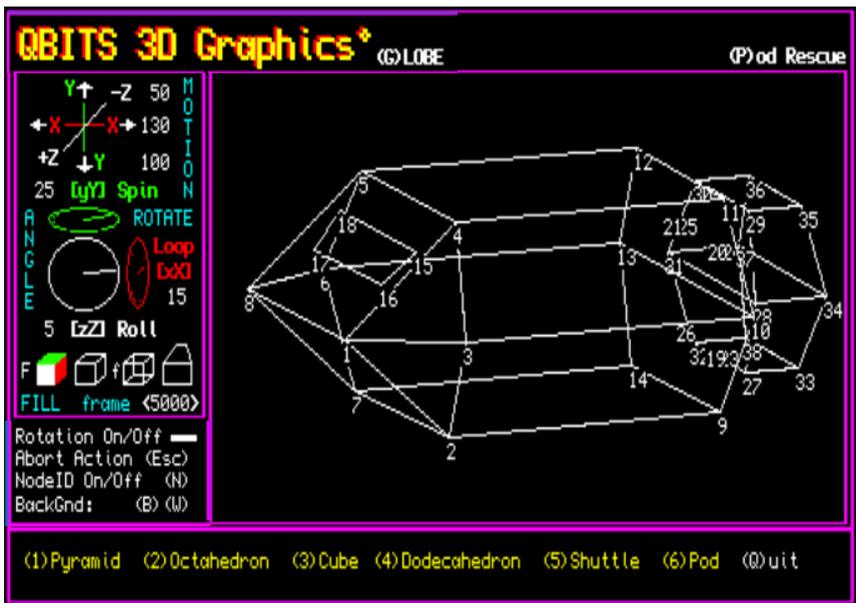




Sinclair QL 3D Rotation Graphics



Sinclair QL 3D Rotation Graphics



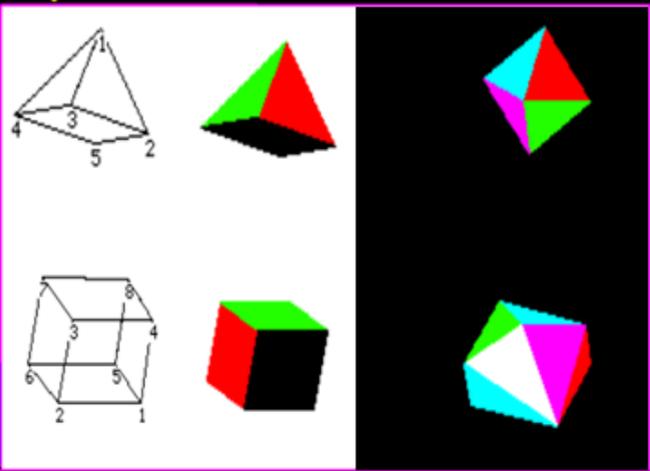
QBITS 3D Graphics*

(G)LOBE

(P)od Rescue

Y ↑ -Z 22 MOTION
 ← X → X → 40
 +Z ↓ Y 170
 55 (y) Spin
 ROTATE
 Loop
 115
 10 (z) Roll
 F
 FILL frame <5000>

Rotation On/Off
 Abort Action (Esc)
 NodeID On/Off (N)
 BackGnd: (B) (W)



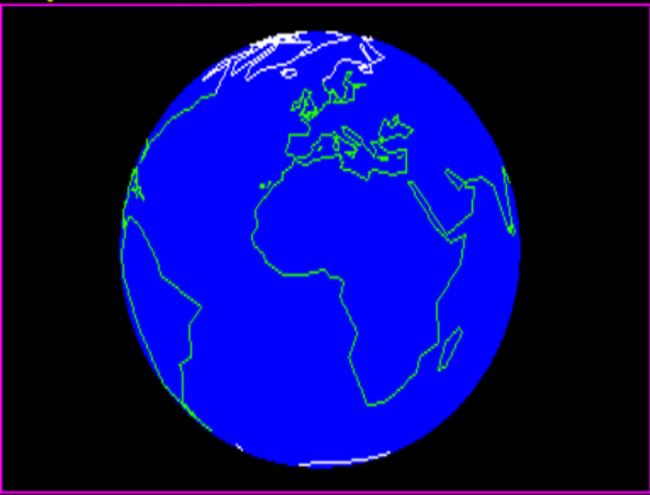
(1) Pyramid (2) Octahedron (3) Cube (4) Dodecahedron (5) Shuttle (6) Pod (0)uit

QBITS 3D Graphics*

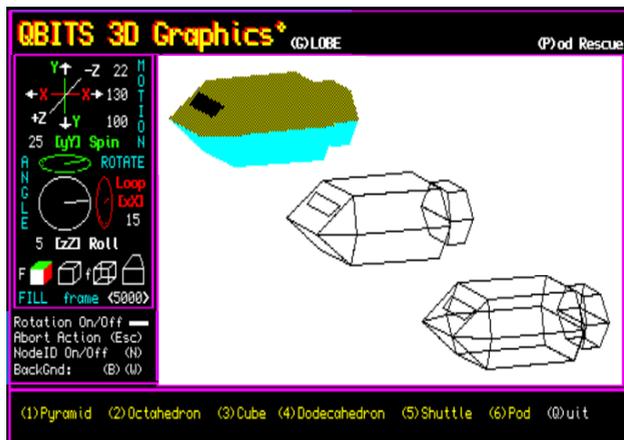
(G)LOBE

(P)od Rescue

(C)ontinents (Esc)
 (1) Europe
 (2) Africa
 (3) Asia
 (4) America Nth
 (5) America Sth
 (6) Australasia
 (7) Arctic
 (8) Antarctic
 (Z) oom
 (U) iewer (Esc)
 (S)et GMT
 (G)rid On/Off
 Radius < >
 Rotate +↑↓
 Rotation On/Off
 Abort Action (Esc)
 NodeID On/Off (N)
 BackGnd: (B) (W)



(1) Pyramid (2) Octahedron (3) Cube (4) Dodecahedron (5) Shuttle (6) Pod (0)uit



Introduction

The availability of home computing in the 1980's sparked myself and others interest in creating computer generated graphics, especially when it involved the manipulation of 3D images. My early attempt to create the illusion of movement began in the mid-eighties writing QL SuperBASIC code to display a 3D Rotating Object a simple Cube. My original QLs performance did not inspire me to continue and the coding was probably a little out of my league at the time, however I did jot down some notes for future review.

QBITS Progs

2023 and my preferred QL Platform is the **QPC2 Emulator**, where in recent years I have upgraded and developed new QBITS Progs. I now have a group of QL SuperBASIC programs accessed via a Menu program named **QBITSProgs**. Each program when actioned by the Menu Loads and starts by importing a common set of variables from a **QBITSConfig** file. This has led to a code Review where future QBITS Progs will be Released with a single format that hopefully runs across a variety of QL platforms.

QBITS 3DGraphics SE

With any upgrade one looks to improve and add more features. This version of Exploring 3D Graphics has a revised display for the action keys and updates of variables as the 3D Object moves through changing positions. A Rescue Pod has been added that can be viewed separately or in combination with the Space Shuttle.

This Special Edition explores further aspects of 3D Rotating Graphics. It includes a simulation where you take control and manoeuvre the Space Shuttle to Dock and Lock with the revolving Rescue Pod [Not as easy a task as you might think

Globe displays a revolving World Map with a Continents Menu to select different areas and a Zoom to enlarge them. Also a Viewer that allows changes to other aspects of the display size, orientation or with/without a longitude/latitude Grid.

QBITS 3DGraphics SE – Control Keys

Images convey more than words so they say, for this revised and Special Edition of Exploring Three-Dimensional Illustrations, Motion and Angle of Rotation are displayed more graphically in a side window.



For **MOTION** along either of the **XX:YY:ZZ** axis lines. **X:Y** is controlled by Left, Right, Up and Down Cursor keys, for **Z** distance near '+' or far '-' keys. The Current **Z X Y** values shown to the right.

For **ANGLE** of Rotation; **nn [yY]Spin** about the **YY** axis shown as a horizontal ellipse above a Circle depicting the **nn [zZ]Roll** about the **ZZ** Axis. To the right **nn [xX]Loop** about the **XX** axis is shown as a vertical ellipse. The current values **nn** displayed with Title.

Upper case 'F' Fills the viewable Fames with Ink Colour. Lower case 'f' Switches between a Solid or Wireframe. Use Left/Right '<'5000'>' Chevron keys to Decrease Increase the Focal Scale range from 250 to 7500.

Spacebar Toggle On/Off Auto **Rotation** of Object.

(**Esc**) Abort Globe / Pod Rescue.

'**N**' Toggles On/Off **Node ID**'s.

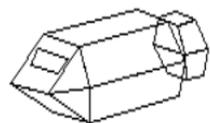
'**B**' '**W**' Switch **BackGnd** between Black or White.

QBITS 3DGraphics SE – Wireframe Objects

Upon selecting one of the Objects (1)(2)(3)(4)(5)(6) the Program first sets up the **Node xyz** coordinates and **Frame** sequences. The 2D Conversion of Vectors are then calculated so that the Wireframe can be displayed to screen. The object can then be manipulated to new positions and display its changing faces (Frames) as it is rotated.



Object (5) & (6) can be displayed separately or together. Choose (5) Shuttle or (6) Pod to view their shapes and manoeuvrability. and check of Node ID's. Then by selecting the other (6) Pod or (5) Shuttle the two are now shown linked together.



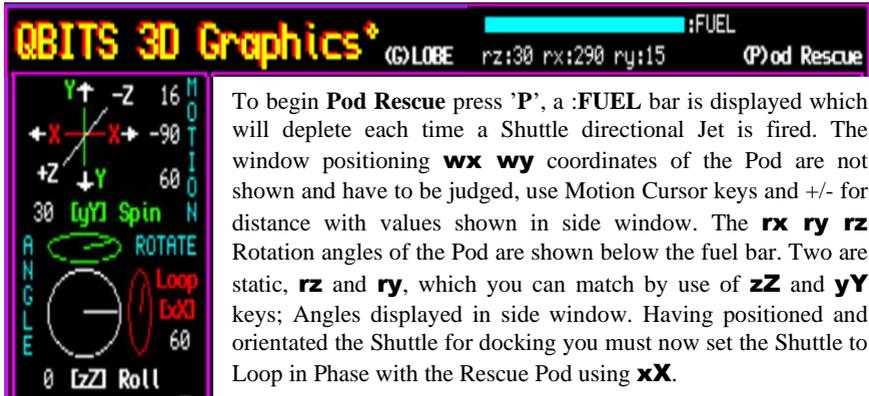
QBITS 3DGraphics SE - Pod Rescue



Shuttle Control

Pod Rescue is where you have to bring under control the Shuttle as it Rotates and moves back and forth across the screen, then manoeuvre it to Dock with the Rescue Pod.

To take control and reposition the Shuttle you will need to fire the Shuttles directional jets so as to reorientate its position for docking with the Rescue Pod. However, each has to be countered with an opposite firing to prevent getting into further uncontrollable Motions and Rotations.



A successful docking ends the simulation.

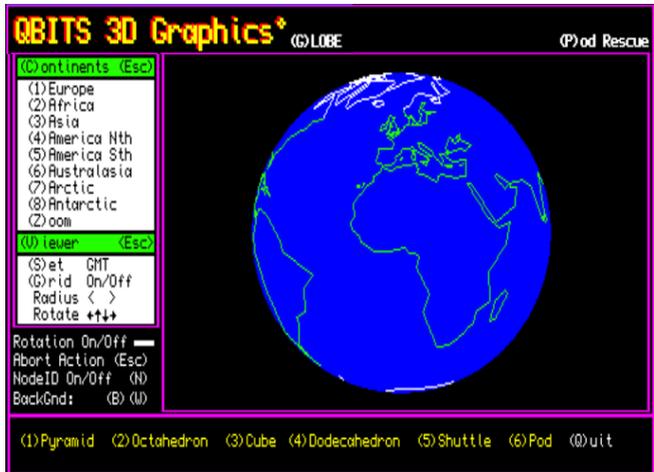


If your unsuccessful you may try again.



Return or Abort Press (Esc) key.

QBITS 3DGraphics SE - Globe



Globe Display

To access press ‘G’ the main window changes to show a World Map of Planet Earth that reveals the different continents as it revolves. Auto Rotation On/Off is controlled by the Spacebar (■). The Side window clears to shows a Menu the (C)ontinents allowing selection of different areas and (V)iewer to change other aspect of the display.

Continents

Select list by pressing ‘C’, the Title bar changes colour to indicate it has been actioned. Then chose an area by pressing (1) to (8). Once an area is chosen you can then Zoom in to enlarge the display.

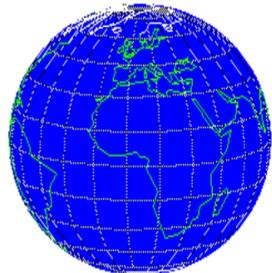


Exit by pressing (Esc) key.

Viewer

Select by pressing ‘V’, the Title bar changes colour to indicate it has been actioned. Pressing ‘S’ [(S)et GMT] returns Map to the prime meridian at Greenwich.

Pressing ‘G’ [(G)rid] toggles Longitude and Latitude Grid lines On/Off.



To reduce or increase Global size use the Left and Right Chevrons [Radius < >]. To Rotate the Globe in various directions, use Left Right Up Down Cursor keys.

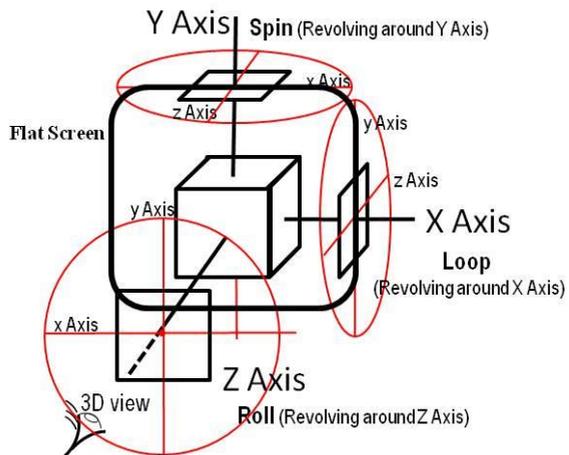
Return by using (Esc) key.

Exploring 3D Graphics

Starting with a two-dimensional object, its outline points of reference are depicted by its x y coordinates. By changing the x y coordinates values a number of x points across the screen (left to right) and by the number of y points (up or down), the object displayed is moved to a new position, this without changing its shape or size is called a translation.

For a three-dimensional object a third coordinate, usually assigned as z is added. Three-dimensional Rotation changes the orientation within each of XX:YY:ZZ relative axis. This alters the shape and size viewed and is known as a transformation. Converting a Three-Dimensional object onto a Two-Dimensional screen image requires transforming of 3D coordinates into 2D coordinates. The coding for such requires a number of steps and involves basic trigonometry.

Depending on what source you refer to or your own background you might come across a few variations on the terms used for 3D rotation. The most common being Roll, Pitch and Yaw associated with flying. I thought of others Rotate, Circulate Orbit, Spin, Loop. For my 3D Rotation Graphics, I decided on Loop, Spin & Roll. All just happen to be four letter words, a little conformity in computer coding always a good thing.



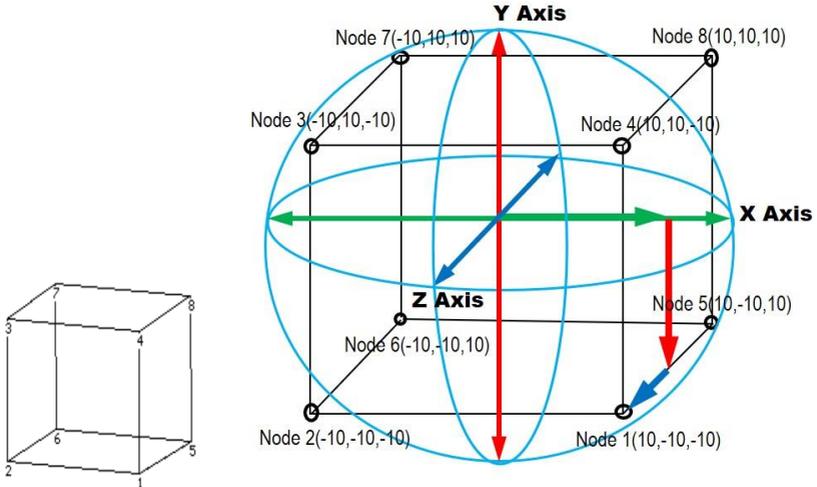
Imaginary Eye View

In viewing the diagram, for a flat screen it is easy enough to imaging the x y coordinates. For three-dimensional space, we need to look at points that lie in front and behind the screen. Using a Cube as our object in space, half of which is sticking out the front of the screen surface, while the other half is lying behind. Looking face on to the screen, you see a square, when you stand over the screen and look straight down you also see a square (half poking out the front, half poking out the back). Looking directly from left or right of the screen, again you see a square half out the front and half out the back.

For each point of reference that connect a 3D Object, be it a simple Cube as shown or a multisided polyhedron, shall be referred to as a Node. These points (Nodes) identify the Objects coordinates so as to Draw a 2D Wireframe as referenced to each of its axis.

Initialising xyz coordinates

The centre of the Cube is given as a Global x y position. Following the Arrows <see below> Node (1) is shown on the X axis as +x units from gy [x=0]. On the Y axis it drops below the gx [y=0] by +y units. Looking down from above we can also see it lies in front of the screen on the Z axis, this places the object closer to us so here we can give it a value of -z units.



	DATA 8	:REMark Number of Nodes
Node (1) xyz	DATA 10,-10,-10	
Node (2) xyz	DATA -10,-10,-10	
Node (3) xyz	DATA -10,10,-10	
Node (4) xyz	DATA 10,-10,10	
Node (5) xyz	DATA 10,10,-10	
Node (6) xyz	DATA -10,10,10	
Node (7) xyz	DATA -10,-10,10	
Node (8) xyz	DATA 10,10,10	

The Node coordinates can now be written as a set of DATA lines, which can used as the basic configuration information. This will apply to not only to our Cube but with any polyhedron and its multiple Nodes.

DIM x(n),y(n),z(n) where **n** is the number of **Nodes** of our polyhedron.

This is the first step to creating our screen image. The next is to consider how these points of reference might move in front of our view point. Drawing a line between points if we Roll the cube on its ZZ axis then we see a square surface turning through 360 degrees. If we Spin the cube around the YY axis then the surface presented changes to show two changing rectangular surfaces before returning to a square. A similar view is presented by Looping around the XX axis. Turning the cube on both XX YY axis the number of surfaces and their shapes change again.

Vector Calculations

To represent a 3D Object onto a 2D screen we use **Vector** Coordinates. These are the calculated **x y** 2D screen positions derived from the Global **x y** set at the centre of our object and correlates to each individual **Node x y z** coordinates.

Trigonometry is used to find the position of a rotating point (**x y**) set around a central origin at a distance (**r**) and by degrees (**a**).

$$x = r \times \text{COS}(a)$$

$$y = r \times \text{SIN}(a)$$

If we then rotate further the angle to b:

$$x' = r \times \text{COS}(a + b)$$

$$y' = r \times \text{SIN}(a + b)$$

By using trigonometric addition of each equation:

$$x' = r \times \text{COS}(a) \text{COS}(b) - r \times \text{SIN}(a) \text{SIN}(b)$$

$$y' = r \times \text{SIN}(a) \text{COS}(b) + r \times \text{COS}(a) \text{SIN}(b)$$

Then substituting in the values for x and y above, we get an equation for the new coordinates as a function of the old coordinates and angle of rotation:

$$x' = x \times \text{COS}(b) - y \times \text{SIN}(b)$$

$$y' = y \times \text{COS}(b) + x \times \text{SIN}(b)$$

The above describes one plane we have three XYZ. For now, we can combine the required function for COS and SIN of the angle to be used with each plane:

$$ra = +.5 : c = \text{COS}(ra) : s = \text{SIN}(ra)$$

Then the code for position in each plane is as follows:

$$yt = y : y = c_x yt - s_x z : z = s_x yt + c_x z \quad \text{X axis (y, z planes)}$$

$$xt = x : x = c_x xt + s_x z : z = s_x xt + c_x z \quad \text{Y axis (x, z planes)}$$

$$xt = x : x = c_x xt - s_x y : y = s_x xt + c_x y \quad \text{Z axis (x, y planes)}$$

Where yt, xt hold the previous x, y coordinate values. The x y z are updated with new values. The 3D coordinates are then transposed into 2D screen positions:

$$vx = wx + (x_x fs) / (z + fs)$$

$$vy = wy + (y_x fs) / (z + fs)$$

Where wx wy are the window coordinates and fs is a scale factor that determines how much we have zoomed in or out from an imaginary focal point.

The above **Vector** calculation for each Node **vx(n)** and **vy(n)** screen coordination again can be stored in a Dimensioned Array.

DIM vx(n),vy(n) where **n** is the same as the number of **Nodes**

We now have our second step whereby 3D positions can be calculated to be represented in a 2D environment. Next is to further process angular movement with changes to the **wx wy** horizontal and vertical positioning and the objects distance as viewed from the view point. This is conveyed by reducing the Object size as it moves away and making it appear bigger as it moves towards the view point.

QBITS 3D Movement & Conversion

Movement is accomplished in various ways. Rotary movement as shown is a change of angle in one of the three planes **xy zy zx Roll/Spin/Loop**. The **zZ xX yY** keys are used by the program to alter the angle for its corresponding plane lower case **zxy** for Anticlockwise and **ZXY** upper case for Clockwise.

For Global repositioning of the Object the **Cursor Left Right Up Down** keys are used to move the **wx wy** coordinates. Distance requires reducing or enlarging the screen image. The process of reading and storing the Nodes **x y z** values gave me the idea of adding a multiplier and thereby being able to increase or reduce an Objects size in a uniform manner. The vector size **vs** is simply that with a range 0.5 to 2.5 in 0.1 increments and controlled by **+/-** keys.

```
DEFine PROCEDURE Obj_Node
LOCAL lp,a,b,c:RESTORE nres
FOR lp=sn TO mn
  READ a,b,c:x(lp)=a*vs:y(lp)=b*vs:z(lp)=c*vs
END FOR lp
END DEFine
```

```
DEFine PROCEDURE Obj_Calc
cx=COS(RAD(rx)):sx=SIN(RAD(rx))
cy=COS(RAD(ry)):sy=SIN(RAD(ry))
cz=COS(RAD(rz)):sz=SIN(RAD(rz))
FOR np=sn TO mn
  yt=y(np):y(np)=cx*yt-sx*z(np):z(np)=sx*yt+cx*z(np)
  xt=x(np):x(np)=cy*xt+sy*z(np):z(np)=sy*xt+cy*z(np)
  xt=x(np):x(np)=cz*xt-sz*y(np):y(np)=sz*xt+cz*y(np)
  vx(np)=wx+(x(np)*fs)/(z(np)+fs)
  vy(np)=wy+(y(np)*fs)/(z(np)+fs)
END FOR np
END DEFine
```

Part of the Object calculations incorporate the Perspective or Focal Scale (**fs**). Imagine a large building from a distance its shape is fairly uniform. Standing at one corner, the height above us as opposed to the height of the building further down the street appears out of proportion to its true measurement. This is what we understand as Perspective, the appearance of things relative to one another as determined by their distance from the viewer and is part of the technique of representing three-dimensional objects on a two-dimensional surface.

Using the **< >** chevron keys **fs** is Decreased or Increased between 250 and 7500. The effect of **fs** at its lower vales enlarges and distorts the Object and can look a little weird.

The fourth step is to correlate the progress made so far. We have **Nodes** and **Vector** representation, **Global Repositioning**, **Axis Rotation** but now need to bring these together and create our Object to screen. To achieve this each side or plane of our object has to be constructed as a Frame.

QBITS 3D Nodes, Vectors & Frames

Displaying a Cube, we begin by reviewing its components. A Cube has eight coordinate points (**Nodes**) and six sides (**Frames**). As with any polyhedron we need to identify the number of **Nodes**, their **xyz** values from which we calculate their **Vector** values **vx vy** for the 2D screen coordinates. Having these we can create each **Frame** from the list of Node coordinates.

QBITS 3D Screen Display

A Frame is the area contained within a set of linked Nodes. A DATA set is used to identify these linked Nodes for the program. The SuperBASIC LINE function can then be used to draw the shape of each to construct a Wireframe of the Object.

	vres	DATA 6
Frame (1) Vector a - b - c - d		DATA 8,7,6,5
Frame (2) Vector a - b - c - d		DATA 2,6,7,3
Frame (3) Vector a - b - c - d		DATA 4,3,7,8
Frame (4) Vector a - b - c - d		DATA 5,1,4,8
Frame (5) Vector a - b - c - d		DATA 5,6,2,1
Frame (6) Vector a - b - c - d		DATA 1,2,3,4

RESTORE vres :READ vn

FOR Frames=1 TO vn

[ie. 6 for Cube]

READ a,b,c,d

LINE vx(a),vy(a) TO vx(b),vy(b) TO vx(c),vy(c) TO vx(d),vy(d) TO vx(a),vy(a)
END FOR node

A FOR loop with **READ** function calls upon the lines of DATA that provide the instruction set to build the Wireframe. The order in which they are presented has a significance that will be explained later when exploring how Wireframe images are turned into Solid images.

QBITS 3D Node ID

At this point it would seem logical to include the ability to identify the Nodes displayed in their screen positions as part of an Objects image. For this Pressing the **N** key toggles On/Off **nset**, which actions the print of Node ID's. For this I make use of the CURSOR graphics coordinate system:

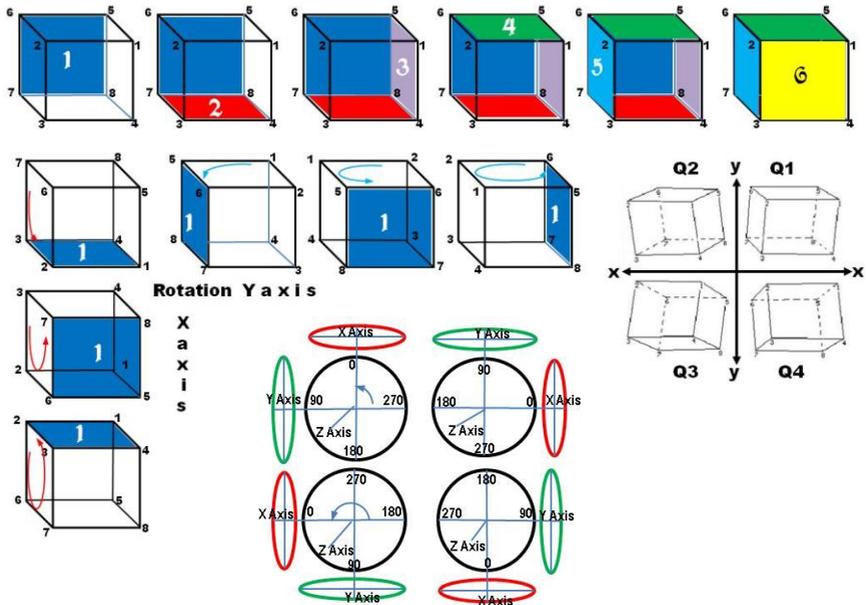
IF nset=2:FOR n=sn TO mn:CURSOR vx(n),vy(n),-2,2:PRINTn

[sn= start node : mn=max node : n being the Node number]

Note: When using the **xxYyZz** keys to Loop/Spin/Roll respectively, once an Object has been rotated from its initial position the Roll/Loop and Spin key commands can act differently to what maybe expected. The positioning of the **ZXY** axis are changed and so rotate in altered planes. An example of this is where the actions of **xx** (Loop) and **yy** (Spin) or **xx** and **zz** act in reversed to each other's original action.

QBITS Notes on XYZ Rotation

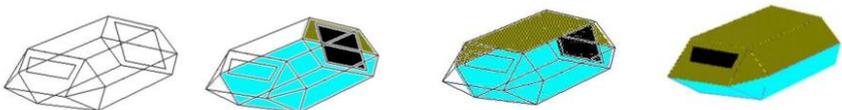
The Frame sequence as hinted before loads those Frames hidden from view first with the ones covering the viewed surfaces last. The problem is as an Object is rotated away from initial settings in any of its three axis then the sequence of Frames hidden from view and those that come into view change. The row of images below shows the initial build and display of Frame surfaces for our Cube, and then the back frame as it **Spins** and **Loops** to different positions on screen, some hidden and some in view.



The screen object is rotated by the actions of **xxYyZz** keys. In the example shown Rotation is around the Z axis. The actions of Spin and Loop change as it moves through each quadrant. Hopefully my diagrams above explain this better than I can put into words. This gives some indication of the complexity you may face when writing code to display the viewable surfaces of a 3D rotating object.

QBITS Wireframe to Solid Object

As a Frame is by definition a closed area, we have the option to leave it unfilled as a Wireframe or coloured in to create a Solid Object using the SuperBASIC FILL function.



This brings us to a fifth step, that is how to remove those Hidden Frames???

QBITS Hidden Surface Removal

In Exploring QL 3D Rotation Graphics I have used planar polygons of which each Frame surface has a unique property. It has two sides, one which looks internally and the other outwardly. Therefore, by determining the outward direction of a frames surface it can be used to see if it is pointing away or towards our view point.

The two basic types of hidden surface removal are Object-space for Three-Dimensional processing and Image-space used for Two-Dimensional processing when determining hidden surfaces.

As the above heading implies a method is sought to remove those hidden surfaces (Frames) of an object to provide a more realistic representation. Namely we seek an algorithm that identifies those Frame surfaces of an object that are not seen from the view point. The most common method used for carrying out this action in computing is called the **Plane Equation Method**.

In simple terms you compute a Vector Normal to a plane (Frame surface) such that its value indicates whether it is facing away from or towards the viewer. I have used the counter or anti-clockwise coordinates system for defining hidden QBITS Frames. This is known as the **Left-handed rule** for the Plane Equation shown below. (There is an alternative called the right-handed or clockwise system)

These are based on the equation: $Ax+By+Cz+D=0$
where the Vector Normal (N) to the plane is $N=[A\ B\ C]$
and where $C > 0$ is a surface facing away
and where $C \leq 0$ is a surface facing towards the viewer.

Obtaining the Vector Normal we use an equation based on the plane passing through three points: $\mathbf{P1}=(x1, y1, z1)$, $\mathbf{P2}=(x2, y2, z2)$, $\mathbf{P3}=(x3, y3, z3)$:

$$\begin{matrix} x - x1 & y1 - y1 & z - z1 \\ x2 - x1 & y2 - y1 & z2 - z1 \\ x3 - x1 & y3 - y1 & z3 - z1 \end{matrix} = 0$$

The matrix equation above is equivalent to: $Ax+By+Cz+D=0$

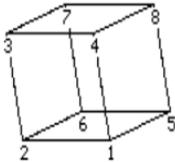
where $C = (x2 - x1)*(y3 - y1) - (x3 - x1)*(y2 - y1)$

C is the value we are interested in to determine the outward facing direction of the Frame surface and whether it is towards or away from the view point.

The last step is to Draw our Object with the option of displaying as a Wireframe or as Solid without//with the viewable planes coloured in. To achieve this, we need to understand how the culling of unwanted Frames are dealt with.

QBITS Anti Clockwise Method

Going back to our Frame DATA lists you will note that the Nodes for the front facing surface are 1,2,3,4 and are ordered in a Clockwise manner and last in the list. The back face 5,6,7,8 is first in the DATA list and ordered as 8,7,6,5 or anti-clockwise. However, if you were to view this surface rotated 180 degrees to the front 8,7,6,5 is then counted in a Clockwise direction and Frame surface 1,2,3,4 is now counted anti-clockwise.



DATA 8,7,6,5,bg2 back Frame [bg2 = Frame surface Colour]
 DATA 2,6,7,3,2
 DATA 4,3,7,8,4
 DATA 5,1,4,8,3
 DATA 5,6,2,1,5
 DATA 1,2,3,4,bg2 front Frame

QBITS 3D Obj_Draw

We now have all the elements required to draw our objects image to screen, the **Node xyz** coordinates, the calculated **Vector vx vy** coordinates, the **Frame** instruction set and a method of eliminating **Hidden** frames.

```
DEFine PROCEDURE Obj_Draw
LOCAL lp,v,a,b,c,d,i:Obj_Node:RESTORE vres:iset=2:Obj_Calc
FOR lp=1 TO vo
  READ a,b,c,d,i : IF cset=1:INK bg2:FILL 0:END IF
  IF cset=2:Obj_Cull:IF c1>0:GO TO 1167:END IF :INK bg2:FILL 0:END IF
  IF cset=3:Obj_Cull:IF c1>0:GO TO 1167:END IF :INK i :FILL 1:END IF
  LINE vx(a),vy(a) TO vx(b),vy(b) TO vx(c),vy(c) TO vx(d),vy(d) TO vx(a),vy(a)
  FILL 0
END FOR lp
IF nset=2:FOR n=sn TO mn:CURSOR vx(n),vy(n),-2,2:PRINT n
END DEFine
```

QBITS 3D Obj_Cull

To calculate the Vector Normal of a Frames surface the points **P1,P2,P3** are substituted with three of a Frames Node **xy** coordinates ie. x(a), y(a) : x(b), y(b) : x(c), y(c)

```
DEFine PROCEDURE Obj_Cull
c1=(x(b)-x(a))*(y(c)-y(a))-(x(c)-x(a))*(y(b)-y(a))
END DEFine
```

QBITS 3D Wireframe Settings

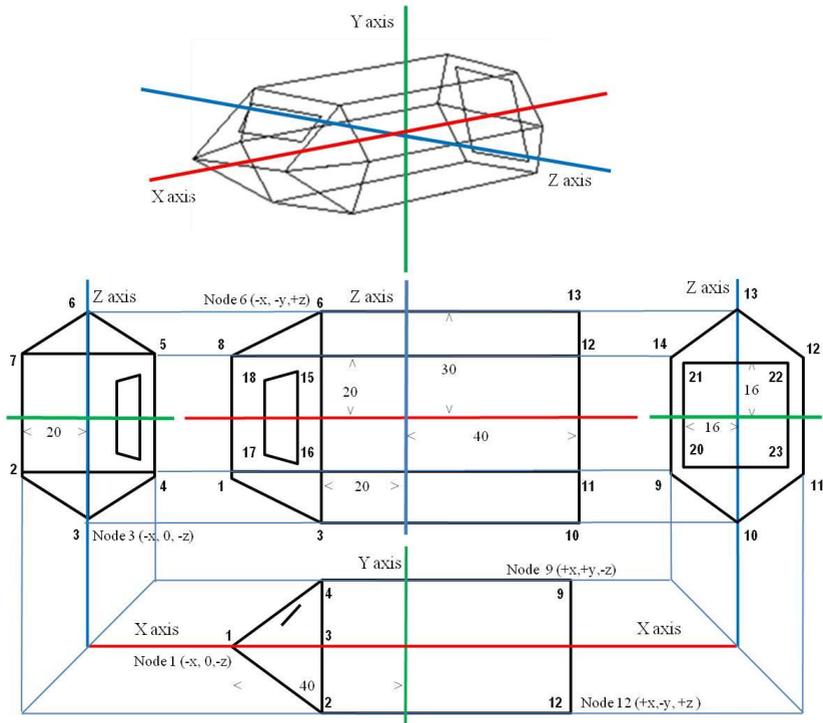
The Wireframe by default outlines all the Frames of an Object with **cset=1**. If **cset=2** the procedure **Obj_Cull** is used to eliminate hidden Frames and a Solid is displayed. If **cset=3** again **Obj_Cull** is used to eliminate hidden frames, but the viewed Frame surfaces are now **FILL**ed. The colour for a Frame surface is the Fifth value entered on the **Frame** DATA Lines (see DATA lines for the Cube above).

For Node ID display 'N' toggles **nset** Off = 1 On = 2. For development of designs the Nodes displayed can be change with **sn** start node & **mn** max node.

QBITS 3D Wireframe Design

To expand on the simple wireframe objects of Pyramid, Diamond, Cube, I have included a simple Space Shuttle design. First the object is drawn schematically shown with front and side elevations. This is then Mapped to the objects **XYZ** planes, with the Nodes (**xyz**) and their relevant units of distance **+/-** values.

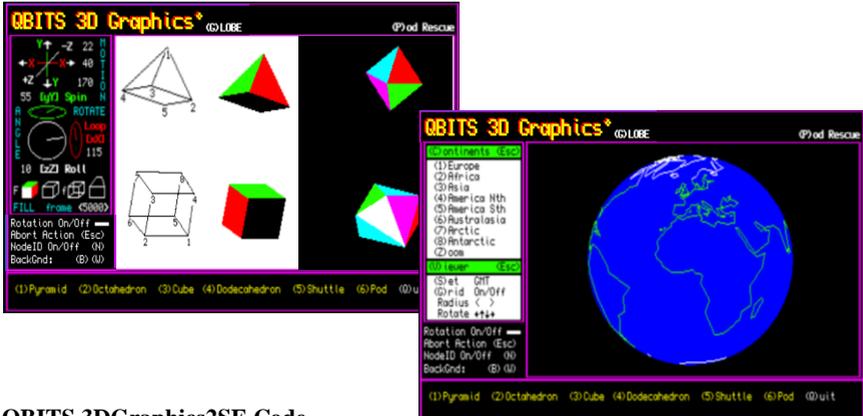
Here's the basic layouts for the Space Shuttle showing values in the **XYZ** planes.



DATA List One can be made for each of the **Node xyz** values. For the Wireframe a **DATA List Two** is required linking Nodes to form **Frames**. These are also READ and used by the Plane Equation of **Obj_Cull** to determine if the outward surface of the polygon is facing towards or away from point of observation. It is therefore important they are seen as ordered correctly, that is Counter or Anticlockwise to viewpoint.

These lists can be added to or created as new **3D DATA Lists** following the Format presented in Program Lines 2000 onwards. Also remember to add in the **RESTORE** references **nres, vres** etc. as part of **Obj_Shape** and their Object **names** into the **Obj_Name** Procedure for screen display and action (number). The action number is entered as part of the **Menu_3DCommnads** (see Line 1081).

QBITS 3D Graphics Special Edition



QBITS 3DGraphics2SE Code

1000 REMark QBITS_3DGraphics2SE_bas (Exploring QL 3D Rotation Graphics2 SE 2023)

1002 MODE 4:gx=0:gy=0 :REMark gx:gy Screen High Res Platforms

1004 wx=0:wy=0:fs=800:vs=8 :REMark win xy:focal scale:vector size

1005 aset=-1:cset=1:nset=1:iset=1 :REMark Toggle switches

1006 bg1=0:bg2=7:k=49 :REMark Screen settings

1008 **WHEN ERROr** : CONTINUE : **END WHEN**

Note: QBITS 3DGraphics is one of a group of QBITS Progs that uses QBITSConfig to input common variables.

1010 OPEN_IN#9,'ram2_QBITSConfig':INPUT#9,gx\gy\dn\$:CLOSE#9

1012 Init_win:Init_QB3D:Obj_Name:Menu_3DCommands

1014 **DEFine PROCedure** Init_win

1015 OPEN#4,con_10x10a10x10_4

1016 OPEN#3,scr_:WINDOW#3,116,150,4+gx,26+gy

1017 WINDOW#2,512,224,gx,gy :BORDER#2,1,3:PAPER#2,0:CLS#2

1018 WINDOW#1,386,196,122+gx,26+gy:BORDER#1,1,3:PAPER#1,0:INK#1,7

1019 WINDOW#0,512,32,gx,224+gy :BORDER#0,1,3:PAPER#0,0:INK#0,7:CLS#0

1020 ch=2:CORSOR#ch,0,0:OVER#ch,1

1021 CSIZE#ch,2,1:str\$='QBITS 3D Graphics'

1022 INK#ch,2:FOR i=0 TO 1:CORSOR#ch,2+i,3:PRINT#ch,str\$

1023 INK#ch,6:FOR i=0 TO 1:CORSOR#ch,4+i,4:PRINT#ch,str\$

1024 CSIZE#ch,0,0 :INK#ch,7

1025 CURSOR#ch,2,178:PRINT#ch,'Rotation On/Off':BLOCK#ch,16,3,98,182,7

1026 CURSOR#ch,2,188:PRINT#ch,'Abort Action (Esc)'

1027 CURSOR#ch,2,198:PRINT#ch,'NodeID On/Off (N)'

1028 CURSOR#ch,2,209:PRINT#ch,'BackGnd: (B)(W)'

1029 OVER#ch,0:ch=3:SCALE#ch,170,0,0:BORDER#ch,1,3

1030 INK#0,7:CORSOR#0,440,8:PRINT#0,'(Q)uit'

1031 **END DEFine**

QBITS 3D Graphics

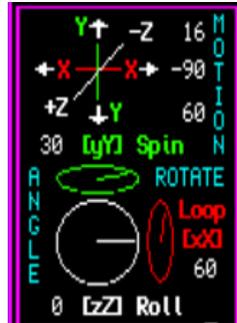
QBITS 3D Graphics Special Edition

1033 DEFine PROCEDURE Init_QB3D

```

1034 LOCAL a,b,c,d,e,f,g,h,j,k
1035 OVER#ch,1:INK#ch,7:CSIZE#ch,2,0:mx=34:my=70:RESTORE 1036
1036 FOR i=1 TO 4:READ a,b,str$:CURSOR#ch,mx,my,a,b:PRINT#ch,str$
1037 DATA -34,-69,'←',+20,-69,'→',-6,-84,'↑',-6,-52,'↓'
1038 OVER#ch,1:CSIZE#ch,0,0:INK#ch,7
1039 FOR i=1 TO 11
1040 READ a,b,c,str$:INK#ch,c
1041 CURSOR#ch,mx,my,a,b:PRINT#ch,str$
1042 CURSOR#ch,mx+1,my,a,b:PRINT#ch,str$
1043 END FOR i
1044 DATA +12,-84,4,'Y',+6,-52,4,'Y',-21,-68,2,'X',+14,-68,2,'X',-28,-54,7,'+Z'
1045 DATA +16,-82,7,'-Z',-10,+20,7,'[zZ] Roll',-10,-40,4,'[yY] Spin'
1046 DATA +42,-5,2,'[xX]',+42,-16,2,'Loop',+39,+52,7,'< >'
1047 OVER#ch,0:INK#ch,5:CURSOR#ch,70,58:PRINT#ch,'ROTATE'
1048 INK#ch,2:LINE#ch,mx-9,my+74 TO mx+11,my+74 :REMark XX
1049 INK#ch,4:LINE#ch,mx,my+62 TO mx,my+86 :REMark YY
1050 INK#ch,7:LINE#ch,mx-10,my+62 TO mx+12,my+86 :REMark ZZ
1051 INK#ch,7:CIRCLE#ch,mx,my,18,1,0 :REMark Roll
1052 INK#ch,4:CIRCLE#ch,mx,my+27,18,.32,PI/2: :REMark Spin
1053 INK#ch,2:CIRCLE#ch,mx+28,my,17,.32,0:INK#ch,5 :REMark Loop
1054 str$='MOTION':FOR i=1 TO 6:CURSOR#ch,100,-8+i*9:PRINT#ch,str$(i)
1055 str$='ANGLE':FOR i=1 TO 1055:CURSOR#ch,4,49+i*9:PRINT#ch,str$(i)
1056 INK#ch,7:CURSOR#ch,2,124:PRINT#ch,'f f'
1057 FOR i=1 TO 12
1058 READ a,b,c,d,e,f,g,h,j,k : INK#ch,j :FILL#ch,k
1059 LINE#ch,a,b TO c,d TO e,f TO g,h TO a,b:FILL#ch,0
1060 END FOR i
1061 DATA 10,15,10,25,20,25,20,15,7,1, 20,15,20,25,25,30,25,20,2,1
1062 DATA 10,25,15,30,25,30,20,25,4,1, 30,15,30,25,40,25,40,15,7,0
1063 DATA 40,15,40,25,45,30,45,20,7,0, 30,25,35,30,45,30,40,25,7,0
1064 DATA 55,15,55,25,65,25,65,15,7,0, 60,20,60,30,70,30,70,20,7,0
1065 DATA 55,15,55,25,60,30,60,20,7,0, 65,15,65,25,70,30,70,20,7,0
1066 DATA 75,15,75,25,90,25,90,15,7,0, 75,25,82,35,87,35,90,25,7,0
1067 INK#ch,5:CURSOR#ch,2,138:PRINT#ch,'FILL frame'
1067 INK#ch,5:CURSOR#ch,2,138:PRINT#ch,'FILL frame'
1068 ch=1:SCALE#ch,200,-143,-100:CSIZE#ch,0,0:INK#ch,4:rx=0:ry=0:rz=0:kch=0
1069 END DEFine

```



Note: Data for building the Graphics

1071 DEFine PROCEDURE QQuit

```

1072 INK#0,7:CURSOR#0,480,8:PRINT#0,'Y/N':PAUSE:IF KEYROW(5)=64:STOP [LRUN dn$]
1073 END DEFine

```



```

1100 DEFine PROCEDURE Menu_3DCommands
1101 REPEAT Com_lp
1102 SElect ON k
1103 =27:
1104 =81,113:QQuit:BLOCK#0,20,10,480,8,0 :REMark (Q)uit
1105 =66,98 :bg1=0:bg2=7:PAPER#1,0:CLS#1 :REMark (B)lack background
1106 =87,119:bg1=7:bg2=0:PAPER#1,7:CLS#1 :REMark (W)hite background
1107 =49 TO 55,71,103,80,112:Obj_Shape :REMark Load Object DATA
1108 =32 :IF aset=-1:aset=5:ELSE aset=-1 :REMark Toggle animation
1109 =102 :IF cset=1 OR cset=3:cset=2:ELSE cset=1 :REMark (f)rame On/Off
1110 =70 :IF cset=1 OR cset=2:cset=3:ELSE cset=1 :REMark (F)ILL On/Off
1111 =78,110:IF nset=1 :nset=2:ELSE nset=1 :REMark (N)ode ID On/Off
1112 =43,61 :vs=vs+.1 :IF vs>=2.5 :vs=2.5 :REMark (+)Increase Vector size
1113 =45 :vs=vs-.1 :IF vs<=.5 :vs=.5 :REMark (-)Decrease Vector size
1114 =62 :fs=fs+50 :IF fs>7500 :fs=7500 :REMark (>)Increase Focal Scale
1115 =60 :fs=fs-50 :IF fs<250 :fs=250 :REMark (<)Decrease Focal Scale
1116 =192 :wx=wx-10 :IF wx<=10 :wx=10 :REMark ← move left
1117 =200 :wx=wx+10 :IF wx>=280 :wx=280 :REMark → move right
1118 =208 :wy=wy+10 :IF wy>=190 :wy=190 :REMark ↑ move up
1119 =216 :wy=wy-10 :IF wy<=10 :wy=10 :REMark ↓ move down
1120 =88 :Obj_Ang:rx=rx-5:IF rx<0:rx=rx+360 :REMark (X)Clockwise Loop
1121 =120 :Obj_Ang:rx=rx+5:IF rx>360:rx=rx-360 :REMark (x)Anti-Loop
1122 =89 :Obj_Ang:ry=ry-5:IF ry<0:ry=ry+360 :REMark (Y)Clockwise Spin
1123 =121 :Obj_Ang:ry=ry+5:IF ry>360:ry=ry-360 :REMark (y)Anti-Spin
1124 =90 :Obj_Ang:rz=rz-5:IF rz<0:rz=rz+360 :REMark (Z)Clockwise Roll
1125 =122 :Obj_Ang:rz=rz+5:IF rz>360:rz=rz-360 :REMark (z)Anti-Roll
1126 END SElect
1127 CLS
1128 IF k1 AND k2
1129 :nres=2099:sn=23:mn=38:vres=2133:vo=10:Obj_Draw
1130 nres=2075:sn=1:mn=21:vres=2115:vo=15
1131 END IF
1132 Obj_Pos:Obj_Draw:INK bg2:k=CODE(INKEY$(#4,aset))
1133 IF aset=5:Obj_Auto:Obj_Ang:PAUSE 5:ELSE Obj_Ang
1134 SElect ON k=49 TO 54,71,103,80,112:BLOCK#2,150,10,280,14,0
1135 END REPEAT Com_lp
1136 END DEFine

```

1112 DEFine PROCEDURE Obj_Pos

Note: Updates the various Position variables

```

1139 ch=3:INK#ch,7
1140 CURSOR#ch,4,106:PRINT#ch,FILL$( ' ',3-LEN(rz))&rz
1141 CURSOR#ch,4,46:PRINT#ch,FILL$( ' ',3-LEN(ry))&ry
1142 CURSOR#ch,84,92:PRINT#ch,FILL$( ' ',3-LEN(rx))&rx
1143 CURSOR#ch,72,18:PRINT#ch,FILL$( ' ',4-LEN(wx))&wx
1144 CURSOR#ch,78,34:PRINT#ch,FILL$( ' ',3-LEN(wy))&wy
1145 CURSOR#ch,84,4:PRINT#ch,FILL$( ' ',2-LEN(vs*20))&vs*20
1146 CURSOR#ch,80,138:PRINT#ch,FILL$( ' ',4-LEN(fs))&fs
1147 END DEFine

```

1149 **DEFine PROCEDURE Obj_Ang**

Note: Displays the Angle changes

```
1150 ch=3:INK#ch,0
1151 FILL#ch,1:CIRCLE#ch,34,70,17,1,0:FILL#ch,0
1152 FILL#ch,1:CIRCLE#ch,34,97,15,.32,PI/2 :FILL#ch,0
1153 FILL#ch,1:CIRCLE#ch,62,70,14,.26,0 :FILL#ch,0
1154 INK#ch,7:LINE#ch,34,70 TO 34+17*COS(RAD(rz)),70+ 18*SIN(RAD(rz))
1155 INK#ch,4:LINE#ch,34,97 TO 34+16*COS(RAD(ry)),97+4.5*SIN(RAD(ry))
1156 INK#ch,2:LINE#ch,62,70 TO 62+ 4*COS(RAD(rx)),70+ 15*SIN(RAD(rx)):ch=1
1157 END DEFine
```

1159 **DEFine PROCEDURE Obj_Auto**

Note: Random Change of Rotation Angles

```
1160 rx=rx+5*RND(1 TO 5):IF rx>=360:rx=0
1161 ry=ry+5*RND(1 TO 5):IF ry>=360:ry=0
1162 rz=rz+5*RND(1 TO 5):IF rz>=360:rz=0
1163 END DEFine
```

1165 **DEFine PROCEDURE Obj_Node**

Note: Load Node coordinates

```
1166 LOCAL lp,a,b,c:RESTORE nres
1167 FOR lp=sn TO mn
1168 READ a,b,c:x(lp)=a*vs:y(lp)=b*vs:z(lp)=c*vs
1169 END FOR lp
1170 END DEFine
```

1172 **DEFine PROCEDURE Obj_Calc**

Note: Calculate the Vectors

```
1173 cx=COS(RAD(rx)):sx=SIN(RAD(rx))
1174 cy=COS(RAD(ry)):sy=SIN(RAD(ry))
1175 cz=COS(RAD(rz)):sz=SIN(RAD(rz))
1176 FOR np=sn TO mn
1177 yt=y(np):y(np)=cx*yt-sx*z(np):z(np)=sx*yt+cx*z(np)
1178 xt=x(np):x(np)=cy*xt+sy*z(np):z(np)=sy*xt+cy*z(np)
1179 xt=x(np):x(np)=cz*xt-sz*y(np):y(np)=sz*xt+cz*y(np)
1180 vx(np)=wx+(x(np)*fs)/(z(np)+fs)
1181 vy(np)=wy+(y(np)*fs)/(z(np)+fs)
1182 END FOR np
1183 END DEFine
```

1185 **DEFine PROCEDURE Obj_Draw**

1186 LOCAL lp,v,a,b,c,d,l : **Obj_Node:RESTORE vres** : iset=2:**Obj_Calc**

```
1187 FOR lp=1 TO vo
1188 READ a,b,c,d,i:IF cset=1:INK bg2:FILL 0:END IF
1189 IF cset=2:Obj_Cull:IF c1>0:GO TO 1193:END IF :INK bg2:FILL 0:END IF
1190 IF cset=3:Obj_Cull:IF c1>0:GO TO 1193:END IF :INK i :FILL 1:END IF
1191 LINE vx(a),vy(a) TO vx(b),vy(b) TO vx(c),vy(c) TO vx(d),vy(d)
1192 LINE TO vx(a),vy(a):FILL 0
1193 END FOR lp
1194 IF nset=2:FOR n=sn TO mn:CURSOR vx(n),vy(n),-2,2:PRINT n
1195 END DEFine
```

Note: sn start node mn max node

1197 **DEFine PROCEDURE Obj_Cull**

```
1198 c1=(x(b)-x(a))*(y(c)-y(a))-(x(c)-x(a))*(y(b)-y(a))
1199 END DEFine
```

Note: Check Frame surface facing view point

QBITS 3D Graphics Special Edition

1201 REMark QBITS Pod Rescue

```
1203 DEFine PROCEDURE Pod_Rescue
1204 DIM Pod(6,5):RESTORE 1206:sk=2      Note: fu = sk [skill level - limits number Fuel use times]
1205 FOR a=1 TO 6:FOR b=1 TO 5:READ num%:Pod(a,b)=num%:END FOR b:END FOR a
1206 DATA 0,0,60,75,45, 30,30,15,-50,45, 15,15,90,-50,80
1207 DATA 15,60,180,-50,-25, 300,90,330,65,-30, 215,330,30,-85,-20
1208 a=RND(1 TO 6):cset=2:vs=5:CLS:Pod_Draw
1209 CURSOR#2,400, 2:PRINT#2,':FUEL':BLOCK#2,120,6,280,4,5
1210 rzp=Pod(a,1):rxp=Pod(a,2):ryp=Pod(a,3):wxp=Pod(a,4):wyp=Pod(a,5)
1211 rx=0:ry=0:rz=0:wx=0:wy=0:vres=2115:vo=16:Obj_Draw
1212 xx=4:yy=6:ax=-5:ay=5:az=-10:ix=2:iy=2:ia=5:fu=sk:Gch=0
1213 REPEAT Main_Ip
1214 IF wy>=wyp-2 AND wy<=wyp+2      Note: IF check statements – alignment of Shuttle with Pod
1215 IF wx>=wxp-2 AND wx<=wxp+2
1216 IF ry>=ryp-5 AND ry<=ryp+5
1217 IF rx>=rxp-20 AND rx<=rxp+20
1218 IF rz>=rzp-5 AND rz<=rzp+5 AND ax=5:Gch=1: EXIT Main_Ip      Note: Docking successful
1219 END IF
1220 END IF
1221 END IF
1222 END IF
1223 BLOCK#2,fu,10,280,4,0:IF fu>=120:Gch=0: EXIT Main_Ip      Note: Docking Unsuccessful
1224 Obj_Ang:Obj_Pos:Get_Keys
1225 IF wx+xx<-125 OR wx+xx>125:xx=-xx
1226 IF wy+yy<-90 OR wy+yy>90:yy=-yy
1227 wx=wx+xx:wy=wy+yy:rx=rx+ax:ry=ry+ay:rz=rz+az      Note: Shuttle Motion variables updated
1228 IF rx+ax<=0:rx=360+ax
1229 IF rx+ax>=360:rx=0+ax
1230 IF ry+ay<=0:ry=360+ay
1231 IF ry+ay>=360:ry=0+ay
1232 IF rz+az<=0:rz=360+az
1233 IF rz+az>=360:rz=0+az
1234 CLS:Pod_Draw:Obj_Draw:IF k=27:Gch=0:EXIT Main_Ip
1235 END REPEAT Main_Ip
1236 BLOCK#2,150,20,280,2,0:k1=1:k2=1
1237 vs=1:wx=0:wy=0:rx=15:ry=30:rz=10:cset=3:aset=-1
1238 IF Gch=0:CURSOR#2,300,14:PRINT#2,'Hard Luck Try Again':Beeps 3
1239 IF Gch=1:CURSOR#2,300,14:PRINT#2,'Successful Docking':Beeps 2
1240 PAUSE 50:PAPER 248:CLS:PAUSE 50:PAPER bg1:CLS
1241 END DEFine

1243 DEFine PROCEDURE Pod_Draw
1244 ow=wx:od=wy:ox=rx:oy=ry:oz=rz:ov=vs
1245 rz=rzp:rxp=rxp+5:ryp=ryp:wx=wxp:wy=wyp:IF rxp>=360:rxp=0
1246 rx=rxp:CURSOR#2,284,14:PRINT#2,'rz:',rz,' rx:',rx,' ry:',ry,' '
1247 nres=2099:sn=23:mn=38:vres=2133:vo=11:Obj_Draw
1248 wx=ow:wy=od:rx=ox:ry=oy:rz=oz:nres=2075:sn=1:mn=22:vres=2115:vo=16
1249 END DEFine
```

Note: Pod_Draw saves current Position, Rotation, then Sets for Rescue Pod. Pod **wx wy** are not given and has to be judged. Pod's **rz & ry** Angles of Rotation are fixed, but **rx** continues to Loop. All three must be matched for a **Successful Docking**.

QBITS 3D Graphics Special Edition

1251 DEFine PROCEDURE Get_Keys

1252 k=CODE(INKEY\$(10)):tx=xx:ty=yy:bx=ax:by=ay:bz=az

1253 SElect ON k

Note: Continuous Motion created by variables xx, yy, ix : ax, ay, az, ai

```

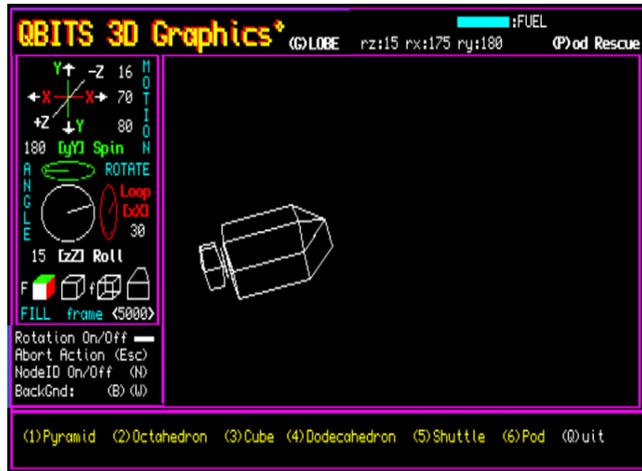
1254 =192:xx=xx -ix      :REMark Left
1255 =200:xx=xx+ix      :REMark Right
1256 =208:yy=yy+iy      :REMark Up
1257 =216:yy=yy -iy     :REMark Down
1258 = 88:ax=ax+ia      :REMark Loop Clockwise
1259 =120:ax=ax -ia     :REMark Loop Anti-clockwise
1260 = 89:ay=ay+ia      :REMark Spin Clockwise
1261 =121:ay=ay -ia     :REMark Spin Anti-clockwise
1262 = 90:az=az+ia      :REMark Spin Clockwise
1263 =122:az=az -ia     :REMark Spin Anti-clockwise
1264 =43,61:vs=vs+.1:IF vs>=.8:vs=.8 :REMark (+)Increase Vector size
1265 =45 :vs=vs -.1:IF vs<=.4:vs=.4 :REMark (-)Decrease Vector size
1266 END SElect
1267 IF xx>11 OR xx<-11:xx=tx      :REMark Move Limits
1268 IF yy> 8 OR yy<- 8:yy=ty
1269 IF ax>15 OR ax<-15:ax=bx      :REMark Angle Limits
1270 IF ay>15 OR ay<-15:ay=by
1271 IF az>15 OR az<-15:az=bz
1272 SElect ON k=88,89,90,120,121,122,192,200,208,216:fu=fu+sk:Beeps 1
1273 END DEFine
    
```

1275 DEFine PROCEDURE Beeps(b)

1276 SElect ON b

```

1277 =1:BEEP 5000,0,500,6,1,2,0,0
1278 =2:BEEP 9500,0,200,6,2,1,0,0
1279 =3:BEEP 30000,1,9,200,-5,8,0,0
1280 =4:BEEP 25000,0,200,8,1,2,0,0
1281 =5:BEEP 3000,0,400,2,1,0,0,0
1282 END SElect
1283 END DEFine
    
```



QBITS 3D Graphics Special Edition

1300 REMark QBITS Globe WorldMap

1302 DEFine PROCEDURE Globe3D

```
1303 PAPER 0:CLS:ch=3:CLS#ch:INK#ch,0:RESTORE 1305:Beeps 4
1304 FOR i=1 TO 15:PAUSE 2:READ a,b,str$:GTitle a,b,str$
1305 DATA 4,2,'(C)ontinents (Esc)',7,14,' (1)Europe',7,23,' (2)Africa'
1306 DATA 7,32,' (3)Asia',7,41,' (4)America Nth',7,50,' (5)America Sth'
1307 DATA 7,59,' (6)Australasia',7,68,' (7)Arctic',7,77,' (8)Antarctic'
1308 DATA 7,86,' (Z)oom',4,98,'(V)iewer <Esc>',7,110,' (S)et GMT'
1309 DATA 7,119,' (G)rid On/Off',7,128,' Radius < >',7,137,' Rotate %¼½'
1310 BEEP
1311 R=90:wrx=0:wry=12:zm=12 :REMark Radius Pixels: x,y Angle coordinates
1312 S=0 :M=0 :P=15 :O=0 :REMark Spin/Meridian/Parallel - Rotation
1313 Gcol=248 :Ccol=4 :Acol=7 :REMark Grid/Coastline - Colours
1314 vh=1 :REMark vh=0 make visible view hidden
1315 REPEAT G_ip
1316 IF KEYROW(1)= 8:PAPER bg1:INK bg2:CLS:EXIT G_ip
1317 IF KEYROW(1)=64:IF aset=-1:aset=5:ELSE aset=-1
1318 IF KEYROW(2)= 8:Continents
1319 IF KEYROW(7)=16:Viewer
1320 S=S+3:World:Calc_ang:Grid:RESTORE 2500:Maps:PAUSE aset
1321 END REPEAT G_ip
1322 END DEFine
```

1324 DEFine PROCEDURE GTitle(icol,ypos,str\$)

```
1325 STRIP#ch,icol:CURSOR#ch,2,ypos:PRINT#ch,str$,FILL$(' ',18-LEN(str$))
1326 END DEFine
```

1328 DEFine PROCEDURE World

```
1329 CLS:INK 1:FILL 1:CIRCLE 0,0,R:FILL 0 :REMark gcol globe colour
1330 END DEFine
```



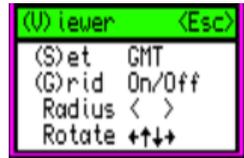
1332 DEFine PROCEDURE Continents

```
1333 GTitle 6,2,'(C)ontinents (Esc)':Beeps 5
1334 REPEAT Choice
1335 k=CODE(INKEY$(-1))
1336 SElect ON k
1337 =27:R=90:GTitle 4,2,'(C)ontinents (Esc)':EXIT Choice
1338 =49:R=90:wrx= 0:wry= 45:S= 15:zm=12 :REMark (1) Europe
1339 =50:R=90:wrx= 0:wry= 6:S= 18:zm= 6 :REMark (2) Africa
1340 =51:R=90:wrx= 0:wry= 45:S= 80:zm= 3 :REMark (3) Asia
1341 =52:R=90:wrx= 0:wry= 50:S= -99:zm= 6 :REMark (4) America Nth
1342 =53:R=90:wrx= 0:wry=-20:S= -60:zm= 6 :REMark (5) America Sth
1343 =54:R=90:wrx= 0:wry=-18:S=134:zm= 6 :REMark (6) Australasia
1344 =55:R=90:wrx= 0:wry= 90:S= 15:zm=12 :REMark (7) Arctic
1345 =56:R=90:wrx= 0:wry=-90:S= 0:zm= 6 :REMark (8) Antarctic
1346 =90,122 :IF R<90+zm*10:R=R+zm :REMark (Z)oom
1347 END SElect
1348 World:Calc_ang:Grid:RESTORE 2500:Maps:INK 0
1349 END REPEAT Choice
1350 END DEFine
```



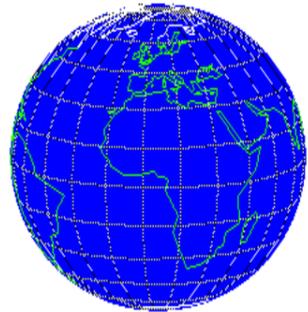
```

1352 DEFine PROCEDURE Viewer
1353 GTitle 6,98,'(V)iewer (Esc):Beeps 5
1354 REPEAT View_Ip
1355 k=CODE(INKEY$(-1))
1356 SElect ON k
1357 =27:GTitle 4,98,'(V)iewer (Esc):EXIT View_Ip
1358 =115,83:wrx=0:wry=0:S=0 :REMark (S)et
1359 =103,71:IF M=0:M=15:ELSE M=0 :REMark (G)rid
1360 = 46,60:IF R<93:R=R+3 :REMark > Radius
1361 = 44,62:IF R>33:R=R-3 :REMark < Radius
1362 =192 :wrx=wrx+6 :REMark Left world radial axis X
1363 =200 :wrx=wrx-6 :REMark Right
1364 =208 :wry=wry+6 :REMark Up world radial axis Y
1365 =216 :wry=wry-6 :REMark Down
1366 END SElect
1367 World:Calc_ang:Grid:RESTORE 2500:Maps:INK 0
1368 END REPEAT View_Ip
1369 END DEFine
    
```



```

1371 DEFine PROCEDURE Grid
1372 INK Gcol:IF M=0 :RETurn
1373 FOR O=M TO 360 STEP M
1374 T=0:FOR L=90 TO -90 STEP -P:Calc_posn
1375 END FOR O
1376 FOR L=-90+g TO 90-g STEP M
1377 T=0:FOR O= 0 TO 360 STEP P:Calc_posn
1378 END FOR L
1379 END DEFine
    
```



```

1381 DEFine PROCEDURE Maps
1382 REPEAT Loop
1383 READ num,col:INK col:T=0 :IF num=9999:EXIT Loop
1384 READ L,O:Calc_posn :REMark Longitude & Latitude Offset
1385 FOR i=2 TO num:READ L,O:T=1:Calc_posn:END FOR i
1386 END REPEAT Loop
1387 END DEFine
    
```

```

1389 DEFine PROCEDURE Calc_ang
1390 sx=SIN(RAD(wrx)):cx=COS(RAD(wrx)) :REMark x coordinates
1391 sy=SIN(RAD(wry)):cy=COS(RAD(wry)) :REMark y coordinates
1392 END DEFine
    
```

```

1394 DEFine PROCEDURE Calc_posn
1395 Ms=SIN(RAD(O-S)):Mc=COS(RAD(O-S)) :REMark O Longitude S Rotation
1396 Pc=COS(RAD(L)) :Ps=SIN(RAD(L)) :REMark L Latitude
1397 wvz=R*(Ps*sy*cx-Pc*Ms*sx+Pc*Mc*cy*cx) :REMark Z axis
1398 wvx=R*(Pc*Ms*cx+Ps*sy*sx+Pc*Mc*cy*sx) :REMark X axis
1399 wvy=R*(Ps*cy-Pc*Mc*sy) :REMark Y axis
1400 IF vh=1 AND wvz<0:T=0 :REMark vh=0 view hidden plane
1401 IF T=0:px=wvx:py=wvy:T=1:RETurn :REMark T=0 Set px,py
1402 IF T=1:LINE px,py TO wvx,wvy:px=wvx:py=wvy :REMark T=1 Draw & Set px,py
1403 END DEFine
    
```

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1950 REMark QBITS Wireframe Data

1952 DEFine PROCEDURE Obj_Name

1953 OVER#2,1:CURSOR#2,0,0:CSIZE#2,0,0:INK#2,7

1954 FOR i=0 TO 1:CURSOR#2,220+i,14:PRINT#2,'(G)GLOBE'

1955 FOR i=0 TO 1:CURSOR#2,432+i,14:PRINT#2,'(P)od Rescue'

1956 OVER#2,0:CSIZE#0,0,0:INK#0,6

1957 CURSOR#0, 6,8:PRINT#0,'(1)Pyramid (2)Octahedron (3)Cube'

1958 CURSOR#0,218,8:PRINT#0,'(4)Dodecahedron (5)Shuttle (6)Pod'

1959 END DEFINE

(1)Pyramid (2)Octahedron (3)Cube (4)Dodecahedron (5)Shuttle (6)Pod (0)uit

1961 DEFine PROCEDURE Obj_Shape

1962 DIM x(40),y(40),z(40),vx(40),vy(40),fr(16,6)

1963 iset=1:Obj_Ang

1964 IF k=49:nres=2001:sn=1:mn= 5:vres=2008:vo= 5:rx=60:ry=30:rz=0

1965 IF k=50:nres=2015:sn=1:mn= 6:vres=2023:vo= 8:rx=15:ry=30:rz=0

1966 IF k=51:nres=2033:sn=1:mn= 8:vres=2043:vo= 6:rx=15:ry=30:rz=0

1967 IF k=52:nres=2051:sn=1:mn= 8:vres=2061:vo=12:rx=15:ry= 0:rz=0

1968 SElect ON k=49 TO 52:k1=0;k2=0

1969 IF k=53:nres=2075:sn= 1:mn=22:vres=2115:vo=16:rx= 0:ry=60:rz=0:k1=1

1970 IF k=54:nres=2099:sn=23:mn=38:vres=2133:vo=11:rx= 0:ry=60:rz=0:k2=1

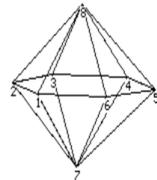
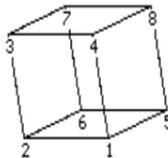
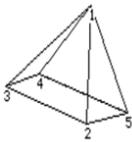
1971 REMark **WARNING** maintain correct nres:vres:RESTORE DATA Lines

1972 IF k=71 OR k=103:Globe3D:CLS#3:STRIP#3,0:Init_QB3D

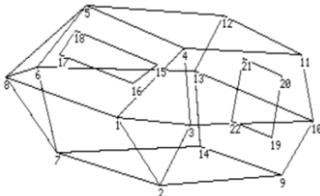
1973 IF k=80 OR k=112:Pod_Rescue

1974 END DEFINE

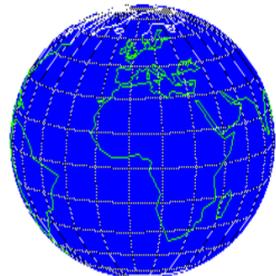
Basic Shapes



Shuttle & Pod



World Maps

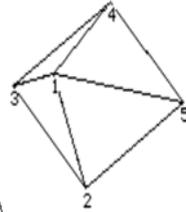


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2000 REMark **Pyramid 5 Nodes**

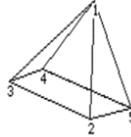
2001 DATA 0, 0, -20
 2002 DATA 20, 20, 20
 2003 DATA 20, -20, 20
 2004 DATA -20, -20, 20
 2005 DATA -20, 20, 20

:REMark Node 1 nearest to view point



2007 REMark **Pyramid 5 Frames**

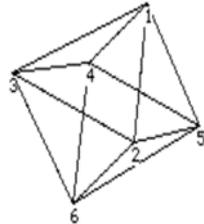
2008 DATA 1,2,3,1,2
 2009 DATA 1,3,4,1,4
 2010 DATA 1,4,5,1,3
 2011 DATA 1,5,2,1,5
 2012 DATA 5,4,3,2,bg2



2014 REMark **Diamond 6 Nodes**

2015 DATA 0, 30, 0
 2016 DATA 20, 0, -20
 2017 DATA 20, 0, 20
 2018 DATA -20, 0, 20
 2019 DATA -20, 0, -20
 2020 DATA 0, -30, 0

:REMark Node 1



:REMark Node 6

2022 REMark **Diamond 8 Frames**

2023 DATA 1,2,3,1,5
 2024 DATA 6,3,2,6,3
 2025 DATA 1,3,4,1,2
 2026 DATA 6,4,3,6,4
 2027 DATA 1,4,5,1,5
 2028 DATA 6,5,4,6,3
 2029 DATA 1,5,2,1,2
 2030 DATA 6,2,5,6,4

:REMark Frame 1

:REMark Frame 8

2032 REMark **Cube 8 Nodes**

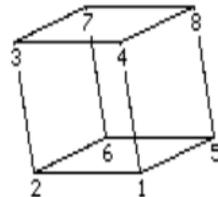
2033 DATA 20, -20, -20
 2034 DATA -20, -20, -20
 2035 DATA -20, -20, 20
 2036 DATA 20, -20, 20
 2037 DATA 20, 20, -20
 2038 DATA -20, 20, -20
 2039 DATA -20, 20, 20
 2040 DATA 20, 20, 20

:REMark Node 1

:REMark Node 4

:REMark Node 5

:REMark Node 8



2042 REMark **Cube 6 Frames**

2043 DATA 8,7,6,5,bg2
 2044 DATA 2,6,7,3,2
 2045 DATA 4,3,7,8,4
 2046 DATA 5,1,4,8,3
 2047 DATA 5,6,2,1,5
 2048 DATA 1,2,3,4,bg2

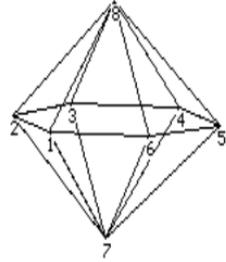
:REMark back Frame

:REMark front Frame

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2050 REMark Polygon 8 Nodes

2051 DATA 32, 0, 0 :REMark Node 1
 2052 DATA 16, 24, 0
 2053 DATA -16, 24, 0
 2054 DATA -32, 0, 0
 2055 DATA -16,-24, 0
 2056 DATA 16,-24, 0
 2057 DATA 0, 0,-32
 2058 DATA 0, 0, 32 :REMark Node 8

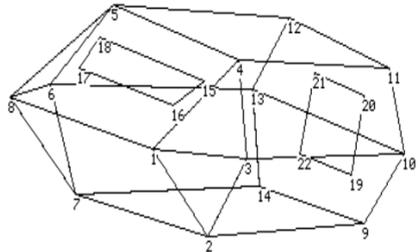


2060 REMark Polygon 12 Frames

2061 DATA 1,2,7,7,6 :REMark 1
 2062 DATA 2,3,7,7,5
 2063 DATA 3,4,7,7,4
 2064 DATA 4,5,7,7,3
 2065 DATA 5,6,7,7,2 :REMark 6
 2066 DATA 6,1,7,7,bg2
 2067 DATA 2,1,8,8,2
 2068 DATA 3,2,8,8,3
 2069 DATA 4,3,8,8,bg2
 2070 DATA 5,4,8,8,5
 2071 DATA 6,5,8,8,6
 2072 DATA 1,6,8,8,4 :REMark 12

2074 REMark Space Shuttle 22 Nodes

2075 DATA -40, 0, 20 :REMark Node 1
 2076 DATA -18,-20, 20 :REMark Node 2
 2077 DATA -20, 0, 30
 2078 DATA -18, 20, 20
 2079 DATA -18, 20,-20
 2080 DATA -20, 0,-30
 2081 DATA -18,-20,-20 :REMark Node 7
 2082 DATA -40, 0,-20 :REMark Node 8
 2083 DATA 38,-20, 20 :REMark Node 9
 2084 DATA 40, 0, 30
 2085 DATA 38, 20, 20
 2086 DATA 38, 20,-20
 2087 DATA 40, 0,-30
 2088 DATA 38,-20,-20 :REMark Node 14
 2089 DATA -24, 14, 16 :REMark Node 15
 2090 DATA -30, 8, 14
 2091 DATA -30, 8,-14
 2092 DATA -24, 14,-16 :REMark Node 18
 2093 DATA 40,-10, 10 :REMark Node 19
 2094 DATA 40, 10, 10
 2095 DATA 40, 10,-10
 2096 DATA 40,-10,-10 :REMark Node 22



Note: Node **xyz** coordinates for Shuttle and Pod are set as part of the same group so they can become one when joined. This is handled by the DATA line references for both Nodes and Frames.

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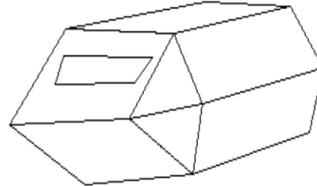
2098 REMark **Rescue Pod 16 Nodes**

2099 DATA 43,-10, 10 :REMark Node 23 1 Hatch
 2100 DATA 43, 10, 10
 2101 DATA 43, 10,-10
 2102 DATA 43,-10,-10 :REMark Node 26 4
 2103 DATA 47,-15, 12 :REMark Node 27 5 Front
 2104 DATA 45, 0, 20
 2105 DATA 47, 15, 12
 2106 DATA 47, 15,-12
 2107 DATA 45, 0,-20
 2108 DATA 47,-15,-12 :REMark Node 32 10
 2109 DATA 58,-15, 12 :REMark Node 33 11 Rear
 2110 DATA 60, 0, 20
 2111 DATA 58, 15, 12
 2112 DATA 58, 15,-12
 2113 DATA 60, 0,-20
 2114 DATA 58,-15,-12 :REMark Node 38 16



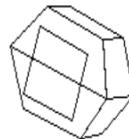
2116 REMark **Space Shuttle 16 Frames**

2117 DATA 9,10,13,14,5 :REMark Rear Frames
 2118 DATA 10,11,12,13,240
 2119 DATA 2,9,14,7,5 :REMark Side Frames ;
 2120 DATA 6,7,14,13,5
 2121 DATA 5,6,13,12,240
 2122 DATA 5,12,11,4,240
 2123 DATA 4,11,10,3,240
 2124 DATA 3,10,9,2,5
 2125 DATA 3,2,1,3,5 :REMark Front Frames
 2126 DATA 1,2,7,8,5
 2127 DATA 7,6,8,7,5
 2128 DATA 8,6,5,8,240
 2129 DATA 4,1,8,5,240
 2130 DATA 1,4,3,1,240
 2131 DATA 15,16,17,18,0 :REMark Pilot Window 15
 2132 DATA 19,20,21,22,191 :REMark Rear Door 16



2134 REMark **Rescue Pod 11 Frames**

2135 DATA 33,34,37,38,5 :REMark Rear Frame 17
 2136 DATA 34,35,36,37,240
 2137 DATA 32,31,28,27,5 :REMark Front Frame 20
 2138 DATA 31,30,29,28,240
 2139 DATA 27,28,34,33,5 :REMark Side Frames 23
 2140 DATA 28,29,35,34,240
 2141 DATA 29,30,36,35,240
 2142 DATA 37,36,30,31,240
 2143 DATA 38,37,31,32,5
 2144 DATA 32,27,33,38,5
 2145 DATA 26,25,24,23,191 :REMark Pod Hatch 28



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2150 REMark Globe Data for World Maps

Note: Each block of Code begins with a **FOR** loop number of entries followed by an **INK** Colour.

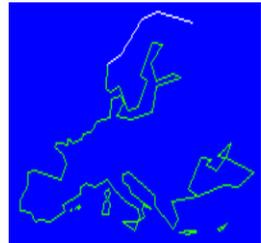
2500 DATA 7,Acol :REMark **Iceland**
2501 DATA 66.5,-22.5,65.4,-24.5,66.6,-16,65,-13.5,63,-19,64,-22,66.5,-22.5



2502 DATA 24,Ccol :REMark **UK & Ireland**
2503 DATA 58.5,-5,58.2,-1.8,56,-3.3,56,-2,53,.5
2504 DATA 53,1.6,52.2,1.7,51.3,.8,51.3,1.5,50,9,1
2505 DATA 50,-5.8,51.4,-3.7,51.7,-5,53.3,-4.5,53.3,-3
2506 DATA 55,-3.5,54.7,-5,57.5,-6.5,58.5,-5
2507 DATA 55.3,-6.5,54.3,-10,51.4,-10,52.2,-6.3,55.3,-6.5 :REMark 48



2508 DATA 89,Ccol :REMark **EUROPE**
2509 DATA 41,29,42,35,41,38,42.5,42.3,46,37 :REMark 10
2510 DATA 48,39,46.5,35,46,37,44.3,34,45.5,32
2511 DATA 46.2,33.5,47,31,42.5,27,41,29,40,8,23
2512 DATA 38,24,36.5,22.8,40.5,19.5,42,19.5,45.7,13.7
2513 DATA 45.5,12.3,44.4,12.3,43.6,13.6,42.5,14.1,40,18.5 :REMark 50
2514 DATA 40.5,17,39.7,16.5,39,17.2,38,15.6,38,12.5
2515 DATA 36.6,15,38.9,16.1,40,15.7,41.3,13,43,10.5
2516 DATA 44.3,8.9,43.2,6.2,43.5,4,42.7,3,41.8,3.3
2517 DATA 39.5,-4,38.7,-3,36.6,-2.1,36.5,-4.8,36,-5.4
2518 DATA 37.1,-6.7,37,-8.8,38.6,-9.4,41.2,-8.6,43.1,-9.3 :REMark 100
2519 DATA 43.7,-7.7,43.3,-1.5,46.1,-1.2,47.3,-2.5,48,-4.7
2520 DATA 48.6,-4.7,48.8,-3.1,48.7,-1.7,49.8,-2,49.8,-1.3
2521 DATA 49.4,-1.1,49.3,-1,49.7,2,50.2,1.5,50.9,1.6
2522 DATA 51.4,3.6,53.3,4.7,54.8,3.5,7,8.1,57.6,10.7
2523 DATA 56.4,11.9,54.5,10,54,14.2,55,20,59,22 :REMark 150
2524 DATA 60,30,60.6,28,60,22,63,21,65.6,26
2525 DATA 66,22,61,17,60,19,56,16,55.4,13
2526 DATA 59,10.3,58,7.6,58.5,6,62.5,5.5 :REMark 176



2527 DATA 5,Acol,62.5,5.5,64,10,70.3,19,71.2,27,67.8,41.5 :REMark Artic area

2528 DATA 10,Ccol :REMark **Corsica & Sardinia**
2529 DATA 43,9.4,42.4,8.5,41.5,8.8,40.9,9.8,39.1,9.7
2530 DATA 38.9,8.4,40.8,8.4,41.3,9.2,42.1,9.6,43.9.4 :REMark 20

2531 DATA 11,Ccol :REMark **Balearic Isles**
2532 DATA 40,3.1,39.9,3.1,39.8,3.2,39.9,3.3,39.8,3.5 :REMark 10
2533 DATA 39.3,3.1,39.4,2.9,39.6,2.8,39.5,2.7,39.4,2.6,40,3.1

2534 DATA 5,Ccol,39.1,1.7,39,1.8,38.9,1.6,39,1.5,39,1.1,1.7 :REMark 10

2535 DATA 6,Ccol :REMark **Cyprus**
2536 DATA 35.5,32,35.6,33,35.9,34,35.2,33,35.2,32,35.6,32

2537 DATA 7,Ccol :REMark **Crete**
2538 DATA 35.8,24,35.9,26,35.7,27.5,35.5,27.5,35.6,26,35.5,26,35.8,24

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2539 DATA 61,Ccol :REMark **AFRICA**
2540 DATA 28,35,28,33,15,40,10.5,45,12,51.4 :REMark 10
2541 DATA 4,47.7,-5,39,-16,41,-20,35,-25,35
2542 DATA -26,33,-29,32,-34,26,-35,20,-18,12
2543 DATA -11,14,-1,9,3,10,4,6,8,4,4,3,5,9
2544 DATA 6,5,4,3,4,8,-2,4,6,-7,7,7,8,-12,9,9,6,-13.4 :REMark 50
2545 DATA 12.4,-16.7,14.9,-17.6,17.2,-16.1,21.3,-17.2,28,-12.9
2546 DATA 30.3,-9.5,31,-9.8,32,-9.8,33,3,-8.3,33.9,-6.9
2547 DATA 35.8,-6,35.9,-5.4,35.2,-4.7,35,-2,36,4,1
2548 DATA 37.3,10.2,36.7,10,4,37,11,36,1,10.5,35,2,11.1
2549 DATA 34,10,32.8,12.5,32.94,13.2,32.4,15.3,31.5,15.6
2550 DATA 30,19,31,20,32,19,7,33,22,31,29
2551 DATA 31.6,31,31.2,33.5,37,36,37,28,40,26,41,29 :REMark 122



2552 DATA 4,Ccol,28.6,-16.1,28,-16.7,28.4,-17,28.6,-16.1 :REMark **Canary Isles**

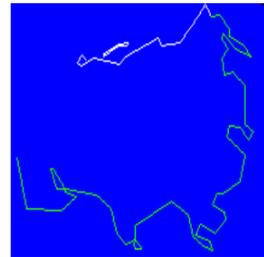
2553 DATA 7,Ccol,29.5,-13.3,29,-13.3,28.8,-14,28,-14.5
2554 DATA 28.3,-13.8,29,-13.7,29.5,-13.4 :REMark 14

2555 DATA 6,Ccol,28.2,-15.6,28.2,-15.4,27.8,-15.3,27.6,-15.7
2556 DATA 27.9,-15.8,28.2,-15.6

2557 DATA 6,Ccol,-13,49,-17,44,-25,44,-25,47,-15,50.5,-13,49:REMark **Madagascar**

2558 DATA 13,Acol :REMark **ASIA**
2559 DATA 66.5,39,67.2,33,64.5,35,64,40,68,2,44
2560 DATA 69,67,72,70,77,112,74,110,72,130
2561 DATA 70,175,67,190,66,177 :REMark 26
2562 DATA 52,Ccol,66,177,63,180,60,170 :REMark **Leave Arctic**

2563 DATA 60,163,55,162,51,157,57,156,62,163
2564 DATA 62,157,59,153,59,143,55,135,54,141
2565 DATA 48,140,39,128,35,129,5,34,126,39,125,5
2566 DATA 41,121,38,5,118,30,122,23,117,21,110
2567 DATA 22,108,19,105,5,14,5,109,11,5,109,8,105
2568 DATA 13,100,5,9,99,5,103,5,1,104,4,101
2569 DATA 9,98,17,97,23,92,15,80,10,80
2570 DATA 8,77,12,74,5,21,72,25,67,25,56
2571 DATA 30,50,29,5,49,24,53,25,56,24,56
2572 DATA 23,60,17,56,12,5,44,28,35 :REMark 104



2573 DATA 7,Acol,77,70,76,60,71,50,70,51,75,60,76,70,77,70:REMark **Novaja**

2574 DATA 7,Ccol :REMark **Sri Lanka**
2575 DATA 9,7,80,7,82,6,5,81,8,6,3,80,5,6,4,80,8,79,7,9,7,80

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2576 DATA 74,Ccol :REMark **AMERICA**
2577 DATA 52,-56,50,-65,46,-64,43.7,-70.4
2578 DATA 41.5,-70.7,40.6,-74,37,-76,35.2,-75.7,31,-81.6
2579 DATA 27,-80,25,-80.5,28,-82.7,29,-82.5,30,-84
2580 DATA 30.3,-89,29,-90,29.7,-94,27,-97.5,22,-97.7
2581 DATA 19,-96,18.4,-94,19,-91.21,-90,21.6,-87 :REMark 50
2582 DATA 16,-89,15.6,-83,10.5,-83.5,9,-81.5,9.7,-79
2583 DATA 8,-77,11,-75,12,-71,10.6,-63,4,-52
2584 DATA 0,-50,-6,-34,-12,-39,-22,-41,-25,-48
2585 DATA -28,-48,-41,-63,-51,-69,-55,-65,-55,-70
2586 DATA -50,-76,-37,-74,-18,-70,-6,-81,0,-81 :REMark 100
2587 DATA 6.6,-77.5,9,-79.7,-81.9,5,-85,13,-88
2588 DATA 14,-91.5,16.2,-95,15.7,-96.6,19.6,-106,22,-105.7
2589 DATA 29,-112.4,31.3,-113,31.6,-115,30,-114.6,23,-109.5
2590 DATA 25,-112.3,30,-115.9,34,-118.5,34.5,-120.7,39,-124
2591 DATA 43,-124.5,48.5,-124.5,59,-138,61,-148,54,-165 :REMark 148



2592 DATA 11,Acol,54,-165,59,-158,62,-166,68,-167,71,-157 :REMark **Arctic**
2593 DATA 68,-110,70,-82,60,-95,54,-80,63,-77,52,-56

2594 DATA 5,Acol,75,-105,73,-90,70,-105,73,-120,75,-105 :REMark **Victoria**

2595 DATA 5,Acol,83,-45,81,-120,78,-105,81,-75,83,-45 :REMark **Elizabeth**

2596 DATA 6,Acol,78,-75,67,-60,60,-60,64,-75,75,-90,78,-75 :REMark **Baffin**

2597 DATA 12,Acol,60,-44,65,-40,70,-22,82 :REMark **Greenland**

2598 DATA -15,83.6,-30,78.5,-73,76,-68,75.6,-59,70

2599 DATA -51,66,-53,5.61,-48,60,-44

2600 DATA 15,Acol :REMark **Arctic Ice sheet**

2601 DATA 77,-114,73,-124,74,-132,76,-130,79,-160

2602 DATA 76,-170,74,176,78,160,83,140,81,110

2603 DATA 82,70,84,30,82,10,76,-10,74,-18 :REMark 30

2604 DATA 18,Ccol :REMark **Caribbean**

2605 DATA 22,-85,23,-83,23,-80.5,20,-74,20,-70

2606 DATA 18.5,-68,18.5,-71,17.5,-71.5,18,-72,18.5,-74.5

2607 DATA 19,-74.5,19,-72.5,20,-74,20,-77.5,20.5,-77

2608 DATA 22.5,-81.5,22,-84,22,-85 :REMark 36

2609 DATA 5,Ccol,18.2,-78.2,18.4,-78,18,-76.2,17.9,-77.8,18.2,-78.2

2610 DATA 5,Ccol,18.5,-67,18.5,-65.5,18,-65,18,-67,18.5,-67

2611 DATA 22,Ccol :REMark **Japan**

2612 DATA 45.5,141.8,43.3,145.7,42,143,42.6,141.6,40.6,140

2613 DATA 38.2,139.6,37,136.9,35.6,135.7,35.6,133.34,130.9

2614 DATA 32.9,132,31.4,131.3,31.2,130.2,33.3,129.7,34,130.9

2615 DATA 34.5,135,33.5,135.7,36,140.6,39.8,142,42.5,139.7

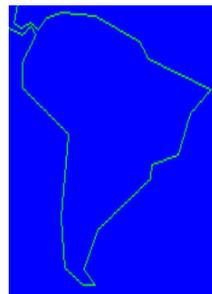
2616 DATA 43.5,141.4,45.5,141.8 :REMark 44

2617 DATA 5,Ccol :REMark **Taiwan**

2618 DATA 25.5,121.5,23.5,120,22,121,25,122,25.5,121.5 :REMark 10

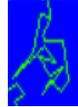
2619 DATA 6,Ccol :REMark **Hainan**

2620 DATA 20,108.6,20,110.3,19.8,110.3,18.3,109.9,18.8,108,20,108.6



QBITS 3D Graphics Special Edition

2621 DATA 19,Ccol :REMark **Philippines**
2622 DATA 21,122,18,122.5,16.5,122.5,15,121.5,14,122
2623 DATA 13.5,125.7,126.5,125.7,123.5,122
2624 DATA 9,125.8,123,11,121,10,124,13,122
2625 DATA 8,117,12,120,18.5,121,18,122.5 :REMark 38



2626 DATA 11,Ccol :REMark **Indonesia**
2627 DATA 6,95,1.7,98.8,-3.2,101.6,-5.9,105.7,-6.6,114.2,-8.6,127
2628 DATA -7.1,105.6,-2.9,105.9,4,103.6,5,97.5,6,95 :REMark 22



2629 DATA 4,Ccol,2,128,1.5,129,-1,128,2,128
2630 DATA 6,Ccol,-3,126,-4,131,-3,130.5,-3,128,-4,126.5,-3,126

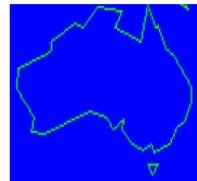
2631 DATA 13,Ccol :REMark **Borneo**
2632 DATA 7,117.5,2.5,111,1.5,111.2,109.5,1,109
2633 DATA -3,110,-4,114.5,-4,116,1,117.5,1,119
2634 DATA 4,117.5,5,119,7,117.5 :REMark 26



2635 DATA 17,Ccol :REMark
2636 DATA 1,125,1,124,1.5,121,0,119.5,-3,118.5
2637 DATA -6,119,-6,120.5,-3,120.5,-5.5,122,-5.5,123
2638 DATA -4,123,-2,121.5,-5,123.5,-1,121,5,120.5
2639 DATA .5,124.5,2,125 :REMark 34

2640 DATA 12,Ccol :REMark
2641 DATA 0,130,-2,134,-2.5,141,-6.5,148,-6.8,146.8
2642 DATA -10.7,151,-7.7,144.3,-9.3,143,-8,138.4,-5.4,138.1
2643 DATA -4,133.1,0,130 :REMark 24

2644 DATA 34,Ccol :REMark **Australia**
2645 DATA -10.5,142.4,-17.5,141,-15,135.5,-12,137,-11,132
2646 DATA -15,129,-14,127,-17.5,122,-19,122,-20,120
2647 DATA -22,114,-26,113,-32,116,-34.5,115,-35.2,118
2648 DATA -31.5,130,-32.5,133.5,-35,135.5,-33,137.8,-35.2,137.5
2649 DATA -38,140.4,-39,143.4,-37.8,145,-39.2,146,-37.5,150
2650 DATA -34,151,-32.7,152.7,-29,153.6,-25.6,153,-20,148.4
2651 DATA -18.8,146.3,-14.5,144.7,-14.7,144,-10.5,142.4 :REMark 68

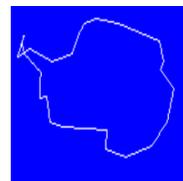


2652 DATA 4,Ccol,-42,144.9,-42,148,-44,146.5,-42,144.9 :REMark Tasmania

2653 DATA 14,Ccol :REMark **New Zealand**
2654 DATA -34.5,172.7,-36.7,175.9,-37.5,176,-38,177.3,-37.4
2655 DATA 178.5,-41.6,175.5,-40.6,172.5,-42.8,171,-46,166.2,-46.7
2656 DATA 169.4,-40.2,175.3,-39.3,174,-37.7,174.8,-34.5,172.7



2657 DATA 29,Acoll :REMark **Antarctica**
2658 DATA -63,-56,-64,-60,-66,-65,-73,-75,-73,-85
2659 DATA -73,-100,-75,-100,-73,-125,-75,-137,-78,-165
2660 DATA -77.6,164,-72,170,-68,155,-66,135,-66,115
2661 DATA -66,90,-69.5,75,-68,70,-66,55,-69,40
2662 DATA -70.20,-70.0,-71,-10,-74,-20,-78,-35
2663 DATA -75,-60,-67,-61,-64.3,-69,-63,-55 :REMark 58
2664 DATA 9999 :REMark End check



QBITS 3DGraphics Procedures

Init_win

Init_QB3D `` Sets screen layout and KEY information. `

Menu_3DCommands Menu loop to access key commands

Obj_Pos Update and display Rotation and Motion variables

Obj_Ang Update Rotation Graphics for Roll, Loop & Spin

Obj_Auto Sets Auto Roll, Loop/ Spin of Object

Obj_Node Loads Node xyz of Object

Obj_Calc Calculates new vx vy coordinates of Object

Obj_Draw Draws Object to screen

Obj_Cull Identifies hidden frames

Pod_Rescue Menu for Pod Rescue Simulation

Pod_Draw Draws Pod and Shuttle for simulation

Get_keys Keys set Rotation and Movement of Shuttle

Beeps(b) Sounds for Shuttle Jets and Docking or Alarm for failure

Globe3D Initiates changes to screen layout set revolving Globe.

GTitle Menu Writes Str\$ to screen

Wold Draws World Circle

Continents Menu to Select and display Continent

Viewer Sets Map display to GMT

Grid Draws Longitude & latitude Grid

Maps Reads DATA and sets angle and position

Calc_ang calculates start angle

Calc_posn Calculates and draws map lines

Obj_Name Displays Object Names and Action tn Screen

Obj_Shape Sets DATA RESTORE references etc for Object.

DATA Lines Basic Shapes, Shuttle, Rescue Pod, World Map

QBITS 3D Graphics Special Edition

The basic Code for Rotation

100 REMark **3D_Cube** (Rotating Cube)

104 MODE 4:WINDOW 512,200,0,0:PAPER 0:INK 4:CLS:SCALE 100,0,0

106 DIM x(8),y(8),z(8),vx(8),vy(8)

108 vl=16 : fs=10000 : ra=.1 :REMark Vector length : Focal Point: Rotation angle

112 CLS

114 x(1)=-vl:y(1)=-vl:z(1)=-vl :REMark Nodes

116 x(2)=-vl:y(2)=+vl:z(2)=-vl

118 x(3)=+vl:y(3)=+vl:z(3)=-vl

120 x(4)=+vl:y(4)=-vl:z(4)=-vl

122 x(5)=-vl:y(5)=-vl:z(5)=+vl

124 x(6)=-vl:y(6)=+vl:z(6)=+vl

126 x(7)=+vl:y(7)=+vl:z(7)=+vl

128 x(8)=+vl:y(8)=-vl:z(8)=+vl

132 ra=ra+.1:c=COS(ra):s=SIN(ra)

136 FOR np=1 TO 8

138 REMark **Rotation on X Axis**

140 yt=y(np):y(np)=c*yt-s*z(np):z(np)=s*yt+c*z(np)

142 REMark **Rotation on Y Axis**

144 xt=x(np):x(np)=c*xt+s*z(np):z(np)=s*xt+c*z(np)

146 REMark **Rotation on Z Axis**

148 xt=x(np):x(np)=c*xt-s*y(np):y(np)=s*xt+c*y(np)

150 REMark **Points Projections and Translations to Screen Coordinates**

152 vx(np)=80+(x(np)*fs)/(z(np)+fs)

154 vy(np)=50+(y(np)*fs)/(z(np)+fs)

156 END FOR np

160 LINE vx(1),vy(1) TO vx(2),vy(2)

:REMark Vectors to Draw a Cube

162 LINE vx(2),vy(2) TO vx(3),vy(3)

164 LINE vx(3),vy(3) TO vx(4),vy(4)

166 LINE vx(4),vy(4) TO vx(1),vy(1)

168 LINE vx(5),vy(5) TO vx(6),vy(6)

170 LINE vx(6),vy(6) TO vx(7),vy(7)

172 LINE vx(7),vy(7) TO vx(8),vy(8)

174 LINE vx(8),vy(8) TO vx(5),vy(5)

176 LINE vx(1),vy(1) TO vx(5),vy(5)

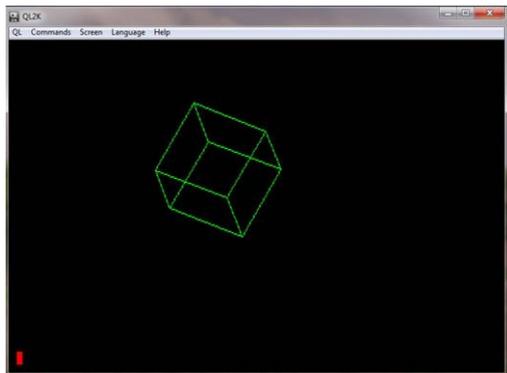
178 LINE vx(2),vy(2) TO vx(6),vy(6)

180 LINE vx(3),vy(3) TO vx(7),vy(7)

182 LINE vx(4),vy(4) TO vx(8),vy(8)

186 PAUSE 5

188 GO TO 112

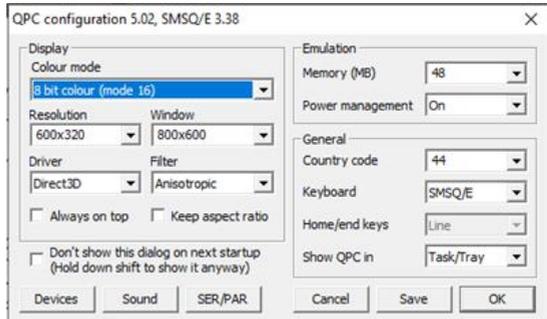


QBITS Progs Development

Most of the QBITS Progs were first envisaged back in the nineteen-eighties, a few were written and released between 1987 and 1992. Those released did undergo updates, but it wasn't until the 2002's when I downloaded a copy of QL2K emulator that I renewed my interest in QL SuperBASIC.

The QBITS Programs exploring 3D Graphics have been developed using various QL Platforms, the latest being the QPC2 v5 Emulator. The QBITS Progs form a group selected from Menu file QBITSProgs where on LRUN they import common variables from a QBITSConfig file. QBITSProgs are by default loaded from QPC2 Device Dos1_.

QPC2 Setting



Background Notes

My aspiration was an efficient code for Rotation of a Wireframe object with Motion to move about the screen altering its global x y position and being able to zoom in and out. Then add Perspective which has something to do focal scale. As a finishing touch FILL the visible surfaces so as the Wireframe Rotates it creates the illusion of a solid object.

Early attempt to code for 3D Graphics began with QB3D_Wire512 which only displayed the Wireframe of a Cube. Further development added controls to alter the screen position horizontally and vertically. Later came the initial trial of **xyz** rotation of the Wireframe. Commands were added to allow manipulation of parameters controlling various aspects of movement, Size and Perspective. The next venture was to create Node and Frame Data to configure four Objects a Pyramid, Cube, Hexagon and a simple Space Shuttle.

While deciding on useful things for the program it occurred to me that a user might prefer a White to a Black background. The Program includes pressing **B** or **W** to change the colour of PAPER (bg1) and INK. (bg2) either a Black background with White INK, or White background with Black INK.

Future Challenges:

To restructure the WorldMap so there are no recursive shapes and FILL used to colour continents. Possibly enhance the Map with more land detail i.e mountain ranges etc.

Write a Companion Program to construct Wireframe Objects and generate their Node **xyz** coordinates and Frame DATA lists would be useful. [03 2023]

QBITS 3D Graphics*

(G)LOBE

:FUEL

rz:215 rx:60 ry:30

(P)od Rescue

MOTION

Y ↑ -Z 16
← X → X → 56
+Z ↓ Y 104

100 (yY) Spin N

ANGLE ROTATE

Loop
Loop
Loop 260

140 (zZ) Roll

F  

FILL frame <5000>

Rotation On/Off

Abort Action (Esc)

NodeID On/Off (N)

BackGnd: (B) (W)



- (1)Pyramid (2)Octahedron (3)Cube (4)Dodecahedron (5)Shuttle (6)Pod (Q)uit

QBITS 3D Graphics*

(G)LOBE

Successful Docking

(P)od Rescue

MOTION

Y ↑ -Z 16
← X → X → 70
+Z ↓ Y 80

180 (yY) Spin N

ANGLE ROTATE

Loop
Loop
Loop 60

15 (zZ) Roll

F  

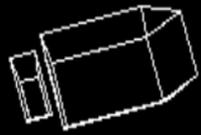
FILL frame <5000>

Rotation On/Off

Abort Action (Esc)

NodeID On/Off (N)

BackGnd: (B) (W)



- (1)Pyramid (2)Octahedron (3)Cube (4)Dodecahedron (5)Shuttle (6)Pod (Q)uit